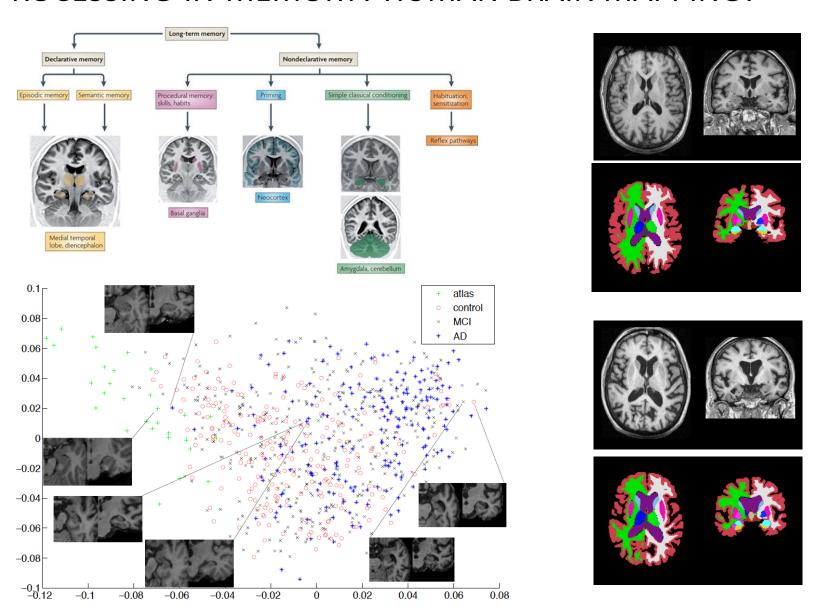


# TOP-PIM: Throughput-Oriented Programmable Processing in Memory

Dong Ping Zhang, Nuwan Jayasena, Alex Lyashevsky
Joe Greathouse, Lifan Xu, Mike Ignatowski
AMD Research
25/06/14

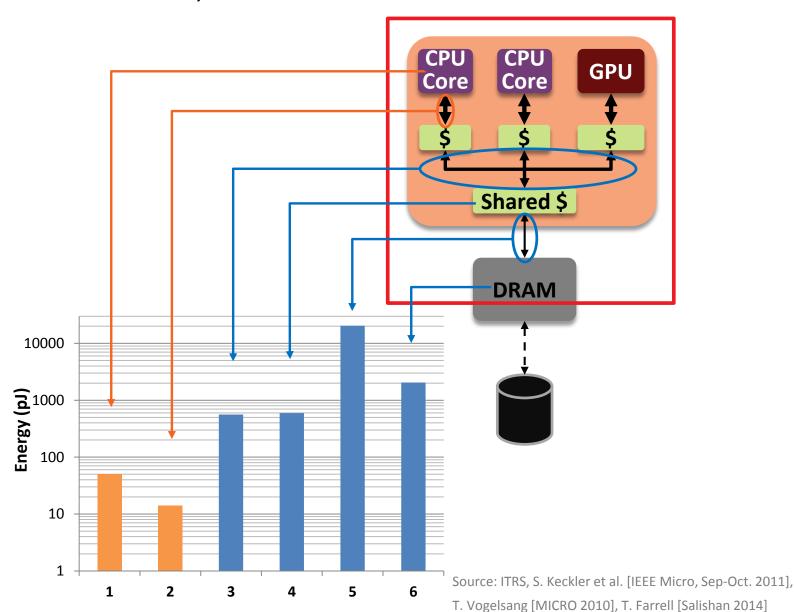
# PROCESSING-IN-MEMORY? HUMAN BRAIN MAPPING?





# COMPUTE IS CHEAP, DATA MOVEMENT IS NOT



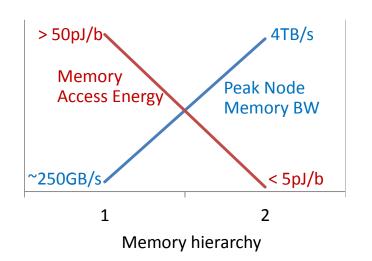


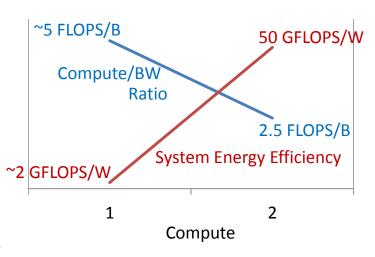
#### **EXASCALE COMPUTING CHALLENGES**



- Energy is the key limiter
  - Exascale system
    - At 4TB/s, vast majority of node energy could be consumed by the memory system
  - 10x reduction in memory energy
  - 25x improvement in system energy efficiency
  - While improving performance
- Need to rethink compute and memory organization
  - Move computation closer to data
  - Specialized support for bandwidth-intensive applications
- ▲ Potential solution: processing-in-memory?

Today: ORNL Titan (node: AMD Opteron+Nvidia Tesla K20X) 2020: DOE FastForward RFP (issued May, 2012) Source: ORNL, Nvidia, top500.org, LLNL





#### **OUTLINE**



- ▲ Background
  - PIM prior work
  - Die-stacking
- ▲ PIM architecture and memory organization
- Applications
  - Graph apps, HPC apps, GPGPU benchmark
- ▲ PIM performance and energy model
- Evaluation of the PIM design choices
- Conclusion and further research

#### PIM RESEARCH – IN THE PAST



- ✓ Prior PIM research constrained by
  - Implementation technology
  - Non-traditional programming models
- Examples of prior work:
  - Integration of caches and computation
    - "A logic-in-memory computer" (1970)
  - Logic in DRAM processes
    - In-memory processors with reduced performance or highly specialized
    - Reduced DRAM due to presence of logic unit
  - Embedded DRAM in logic processes
    - Not cost-effective to have sufficient memory capacity, reduced DRAM density

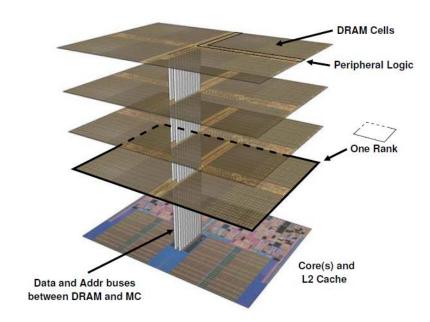
#### Recent work:

- Micron's Automata Processor
- 3D stacked processor for accelerating 3D ultrasound beamformation
- Specialized in-stack processor to accelerate MapReduce workloads

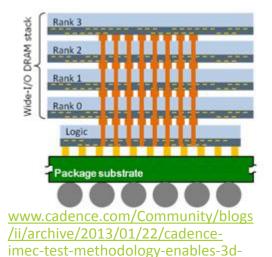
# **3D INTEGRATION**



- Logic die under DRAM using TSVs
  - Higher bandwidth, lower access power
- Significant industry momentum
  - Recent JEDEC standards (HBM, Wide I/O 2)
  - Hybrid Memory Cube (HMC) consortjum
    - Micron, Samsung, IBM, ARM, Xilinx, Altera etc.



Gabe Loh, 3D-Stacked Memory Architectures for Multi-Core Processors, ISCA 2008



ic-memory-on-logic.aspx

http://www.engadget.com/2013/04/03/hybridmemory-cube-receives-its-finished-spec/

#### PIM RESEARCH – NEW PERSPECTIVE



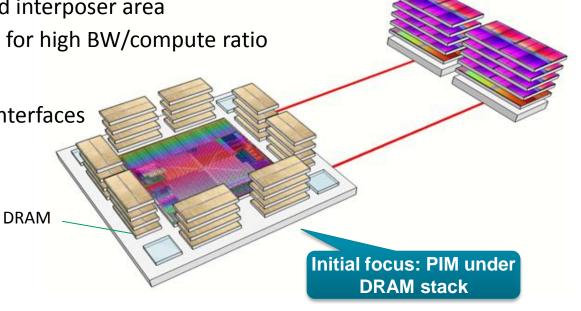
- New opportunity: logic die stacked with memory
  - Logic die needed anyway for signal redistribution and integrity
  - Potential for non-trivial compute

## ▲ Key benefits:

- Reduce bandwidth bottlenecks
- Improve energy efficiency
- Increase compute for a fixed interposer area
- Processor can be optimized for high BW/compute ratio

## ▲ Challenges:

- Programming models and interfaces
- Architectural tradeoffs
- Application refactoring



#### GUIDING PRINCIPLES OF AMD'S PIM RESEARCH



#### Our focus

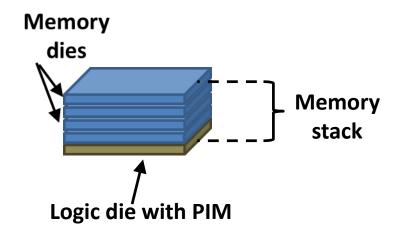
- 3D die stacking
- Use base logic die(s) in memory stack
  - General-purpose processors
  - Support familiar programming models

#### ▲ Ease of use

- Support familiar programming models
- Build on HSA fundamentals
- Any processor (host or PIM) can access all memory on node
- No significant application change for host and PIM.

# Broad applicability

- Across a broad range of applications
- Viable across multiple market segments

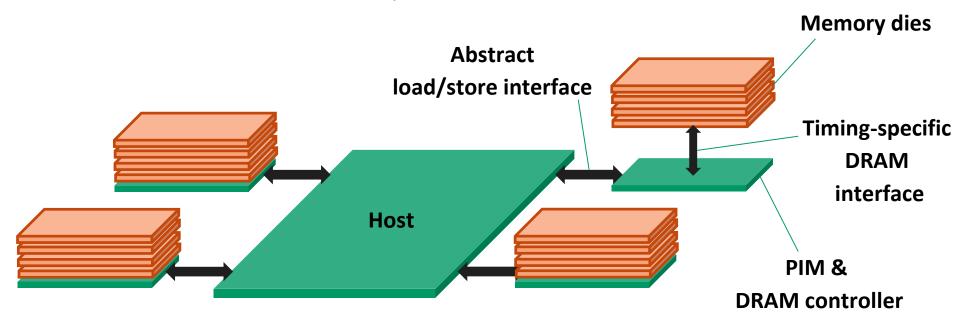


# BASELINE PIM ARCHITECTURE



**AN OVERVIEW** 

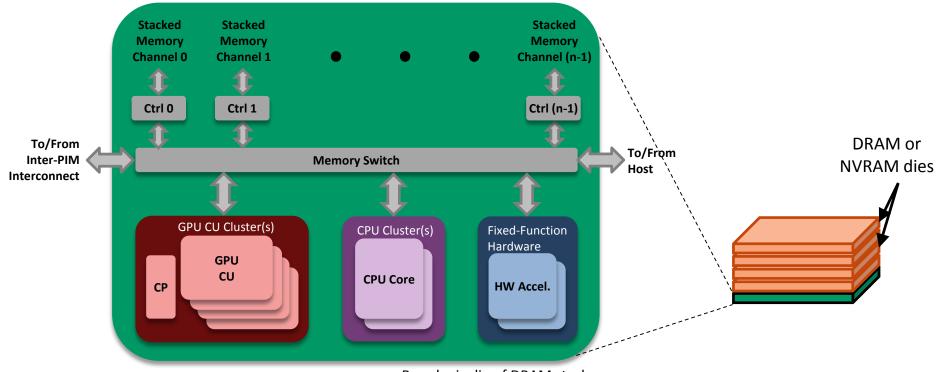
- ▲ An in-memory processor incorporated on the base die of each memory stack
- No DRAM die stacked on host processor



#### BASELINE PIM ARCHITECTURE



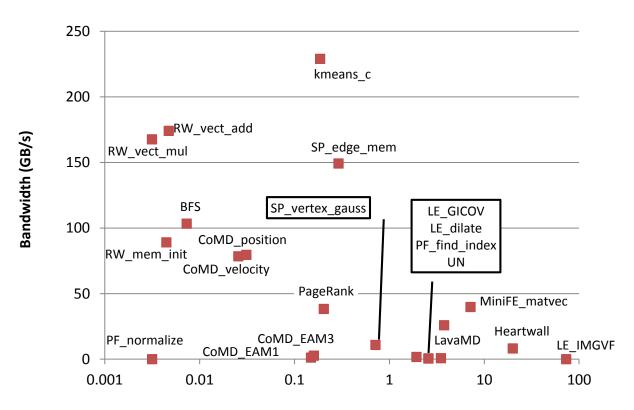
- GPU CUs provide compute throughput
- ▲ CPU cores provide control and flexibility
- Optional fixed-function accelerators



## EXPLORE BREADTH OF APPLICABILITY OF PIM



- Broad set of kernels from HPC apps, graph algorithms, GPGPU benchmarks etc.
- Analyzed using PIM GPU performance and energy models



**Vector Instructions per second (millions)** 

PF = ParticleFilter

SP = ShortestPath

RW = RandomWalk

LE = Leukocyte

# WHY A NEW SIMULATOR?



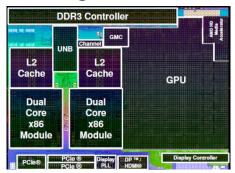
- Why spend time building a new simulator when we could have used:
  - SimNow, TSIM, gem5, Multi2Sim, MARSSx86, PTLsim, Zesto, FeS2, RSIM, ZSIM, Graphite, Flexus, SESC, SST, GPGPUSim, MacSim, Simics+GEMS, SimpleScalar......
- Because they don't answer the question we want to ask
  - Runtime overhead too high
  - Changes take too long to implement
  - Memory overheads preclude large working sets
- ▲ As a result: they can't test the PIM design space on applications that matter
- PIM Simulator trades off some accuracy for major performance improvements

#### CHALLENGES OF MODELING FUTURE SYSTEMS



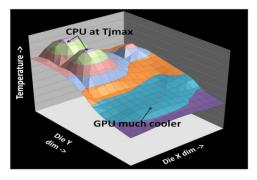
#### LARGE DESIGN SPACE TO EXPLORE

#### Heterogeneous Cores



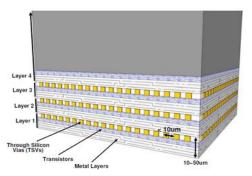
Composition? Size? Speed?

#### Thermal Constraints



Power Sharing? Heat dissipation? Sprinting?

#### **Stacked Memories**



Useful? Compute/BW Ratio? Latency? Capacity? Non-Volatile?

#### Software Co-Design

```
Real t yol = yolo[i] *ynew[i] ;
Real t norm = (Real t)(1.0) / (yol + ptiny);
Real_t dxj = (Real_t)(-0.25)*(SUM4(x0,x1,x5,x4) - SUM4(x3,x2,x6,x7));
Real t dyj = (Real t)(-0.25)*(SUM4(y0,y1,y5,y4) - SUM4(y3,y2,y6,y7));
Real t dz_j = (Real t)(-0.25)*(SUM4(z0,z1,z5,z4) - SUM4(z3,z2,z6,z7));
Real t dxi = (Real t)(0.25)*(SUM4(x1,x2,x6,x5) - SUM4(x0,x3,x7,x4));
Real_t dyi = (Real_t)(0.25)*(SUM4(y1,y2,y6,y5) - SUM4(y0,y3,y7,y4));
Real t dzi = (Real t)(0.25)*(SUM4(z1,z2,z6,z5) - SUM4(z0,z3,z7,z4));
Real t dxk = (Real t)(0.25)*(SUM4(x4,x5,x6,x7) - SUM4(x0,x1,x2,x3));
Real t dyk = (Real t)(0.25)*(SUM4(y4,y5,y6,y7) - SUM4(y0,y1,y2,y3));
Real t dzk = (Real t)(0.25)*(SUM4(z4,z5,z6,z7) - SUM4(z0,z1,z2,z3));
```

New algorithms? Data placement? Programming models?

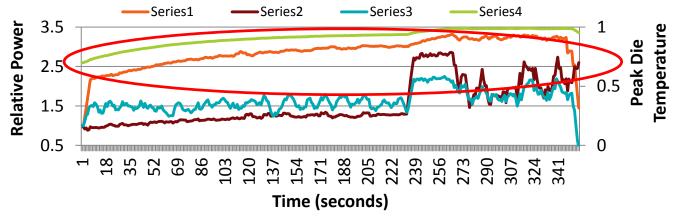
Ref: J. Greathouse et al. Simulation of Exascale Nodes through Runtime Hardware Monitoring, ModSim, 2013

#### CHALLENGES OF MODELING FUTURE SYSTEMS



#### WHY DOES SIMULATOR PERFORMANCE MATTER?

- Need to run long enough to trigger interesting memory phenomena
  - Working sets >> stacked memories of 100s of MB to multiple GB
- Run long enough to observe power and thermal effects
  - Example measured on a real heterogeneous processor

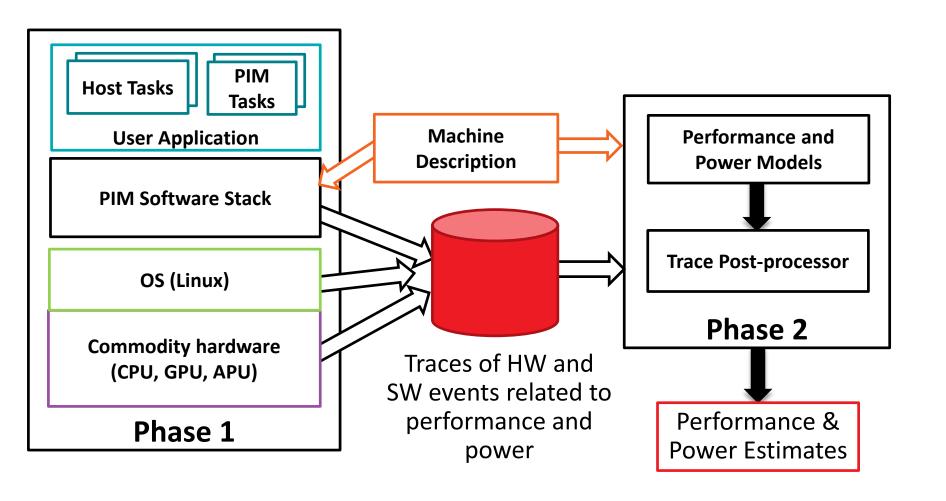


- ~2.5 trillion CPU instructions, ~60 trillion GPU operations
- Applications of interest can be large
  - Scaled studies can be challenging and misleading for complex applications

## PIM SIMULATOR OVERVIEW



MULTI-STAGE PERFORMANCE ESTIMATION PROCESS



#### ML-BASED PERFORMANCE MODEL



- $\triangle$  Execution time <--- F (architecture, application)
  - Kernel time (and power) depends on:
    - Underlying HW configuration
    - Algorithms and data structures of the application
- ▲ PIM GPU Architecture is represented by:
  - Number of CUs (8, 16, 32)
  - Processor frequency (500 100 1000 MHz)
  - Memory Bandwidth (500 100 1300 MHz)

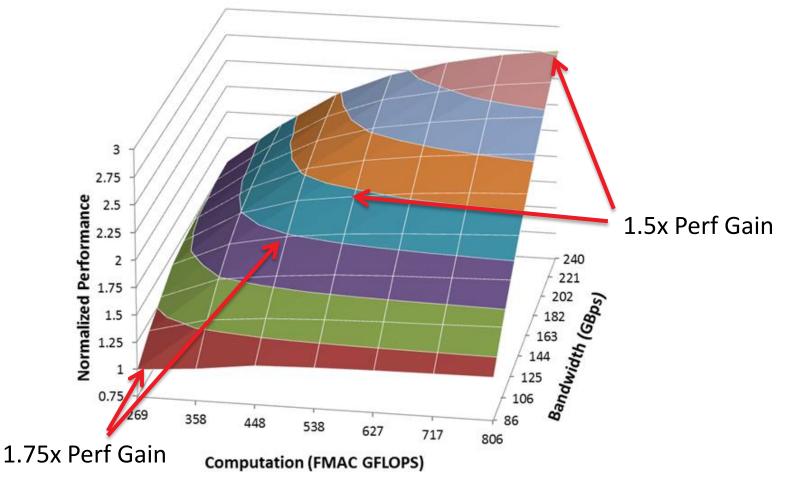
162 design points

- ▲ Application kernel is represented by feature vectors
  - Dynamic CodeXL/Sprofile data, derived from HW counters.
- Goals:
  - Learn scaling pattern in offline training
  - Estimate runtime and power for online prediction

#### PERFORMANCE MODEL – OFFLINE LEARNING



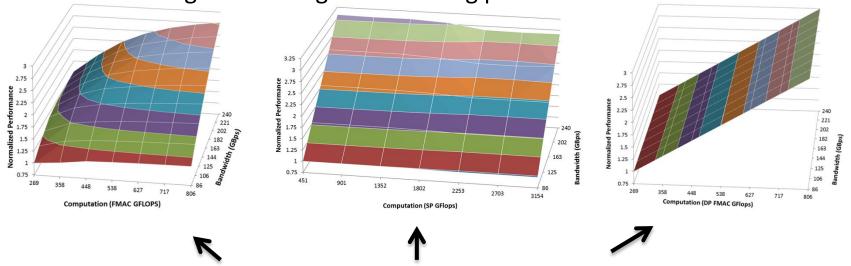
- Gathering data
  - 70 OpenCL kernels
  - Each kernel: 162 hw configurations → 162 pairs of execution time & performance counter feature vector



#### PERFORMANCE MODEL

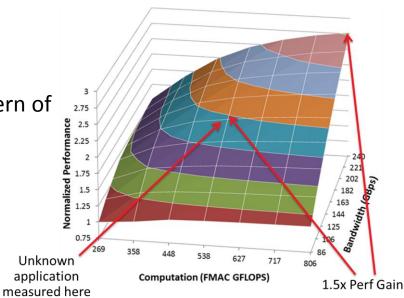


✓ Offline learning – clustering of the scaling pattern



Feature vector: VALUUtilization, VALUBusy, SALUBusy, MemUnitBusy, MemUnitStalled, CacheHit, ...

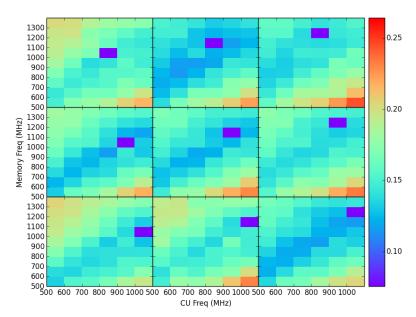
- Online classification and prediction
  - Classify the feature vector of the new kernel
  - Performance projection with the scaling pattern of this cluster



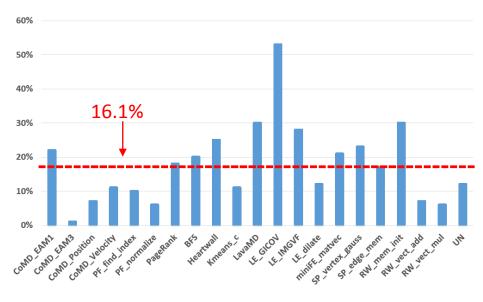
#### PERFORMANCE MODEL VALIDATION



- 69 training kernels; leave one kernel out → prediction → validation.
  - relative error between the prediction and real processing: accuracy verification
- Make predictions for all other HW design points from each design point
  - Variation of #CUs, bandwidth, engine frequency -> 162 operating points -> 162\*161 (26K)
     data points on the 3D grid for each kernel!



Average prediction error - subset



Individual benchmark prediction errors

#### **TECHNOLOGY AND CONFIGURATIONS**

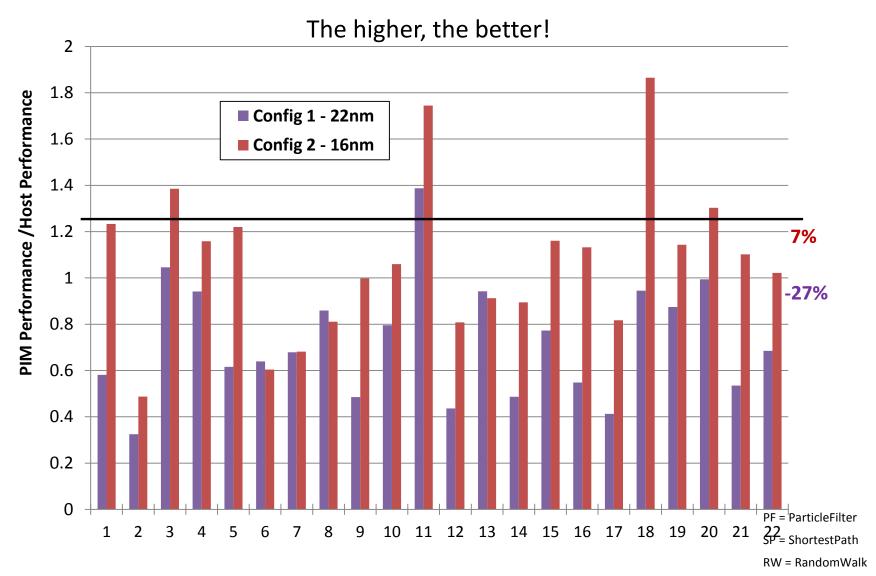


- Evaluated for 22nm and 16nm
  - Explore viability prior to Exascale timeframe
  - Identify tech transfer opportunities
- Design points and technology scaling
  - PIM: limited by DRAM footprint and 10W/PIM
  - Host: extrapolate current trends (assumes HMC-like DRAM interface)

	Baseline	22nm		16nm	
	dGPU	Host	PIM	Host	PIM
Freq	1GHz	1GHz	650MHz	1GHz	650MHz
Number of CUs	32	32	8	64	12
Number of memory stacks		2		4	
DRAM BW (GB/s)		160	640	160	640
Dynamic power scaling	1.00	0.61	0.25	0.41	0.17
Memory Energy (pJ/64b)		522	159	520	155

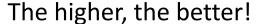
#### PIM CAN BE PERFORMANCE-COMPETITIVE WITH HOST

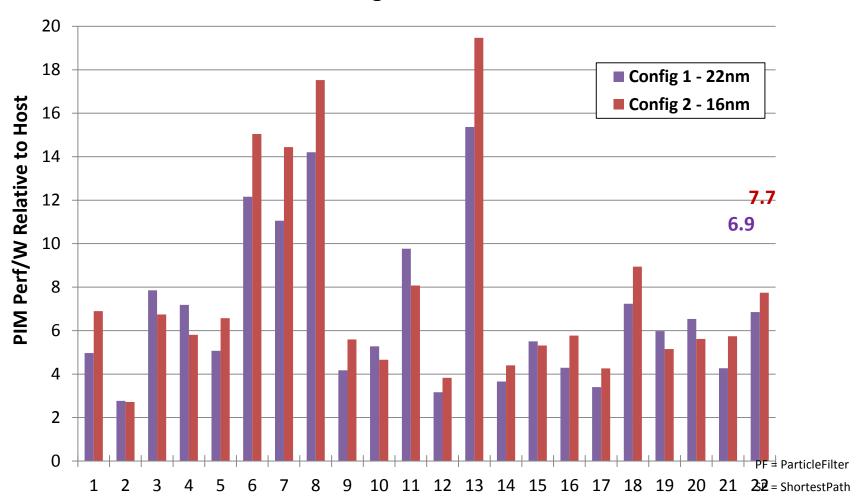




# SIGNIFICANT PERF/W IMPROVEMENTS







#### CONCLUSIONS AND FURTHER RESEARCH



- "Computing" is increasingly about data and data movement
  - Exploit locality to reduce wasteful data movement
  - Specialization to improve efficiency
  - PIM potentially provides significant reductions in off-chip traffic.
- ▲ TOP-PIM implemented using 3D die-stacking feasible in near future.
  - Efficiently utilize the high bandwidth available in local stack
  - Programmability -> Support a broad range of applications
  - Performance and energy efficiency of PIM vs Host
    - At 22nm, 27% performance degradation, 76% reduction in EDP
    - At 16nm, 7% performance gain, 85% reduction in EDP.

#### ▲ Future Work:

- High level programming models to express data-compute affinity.
- Data movement management and task scheduling for host and PIMs.
- Evaluation of alternative PIM organizations and design options.

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